



MÜLLER VIBRATION TECHNOLOGY TECHNICAL DATA

Optimal machinery and equipment are the key to cost-effective work in infrastructure and engineering projects.

We supply our customers with the complete range of machinery and equipment for driving and extracting of steel sheet piles, tubular piles, beams, and other piling sections for light to heavy pile driving jobs. We also provide a convincing technical concept and ensure that the project is executed cost-effectively.

Depending on the on-site requirements, we offer our customers a broad spectrum of suitable machinery, with a range of variants and performance variables, turning as well to our own products such as MÜLLER pile driving and extracting equipment and our excavator-mounted drill drives.

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Characteristics

The selection of a suitable vibratory hammer depends mainly on the size and weight of the pile, the driving depth and the existing soil. In principle, the centrifugal force and amplitude must be selected so that the surface friction and the tip resistance between the pile and the surrounding soil can be overcome.

Selection guide

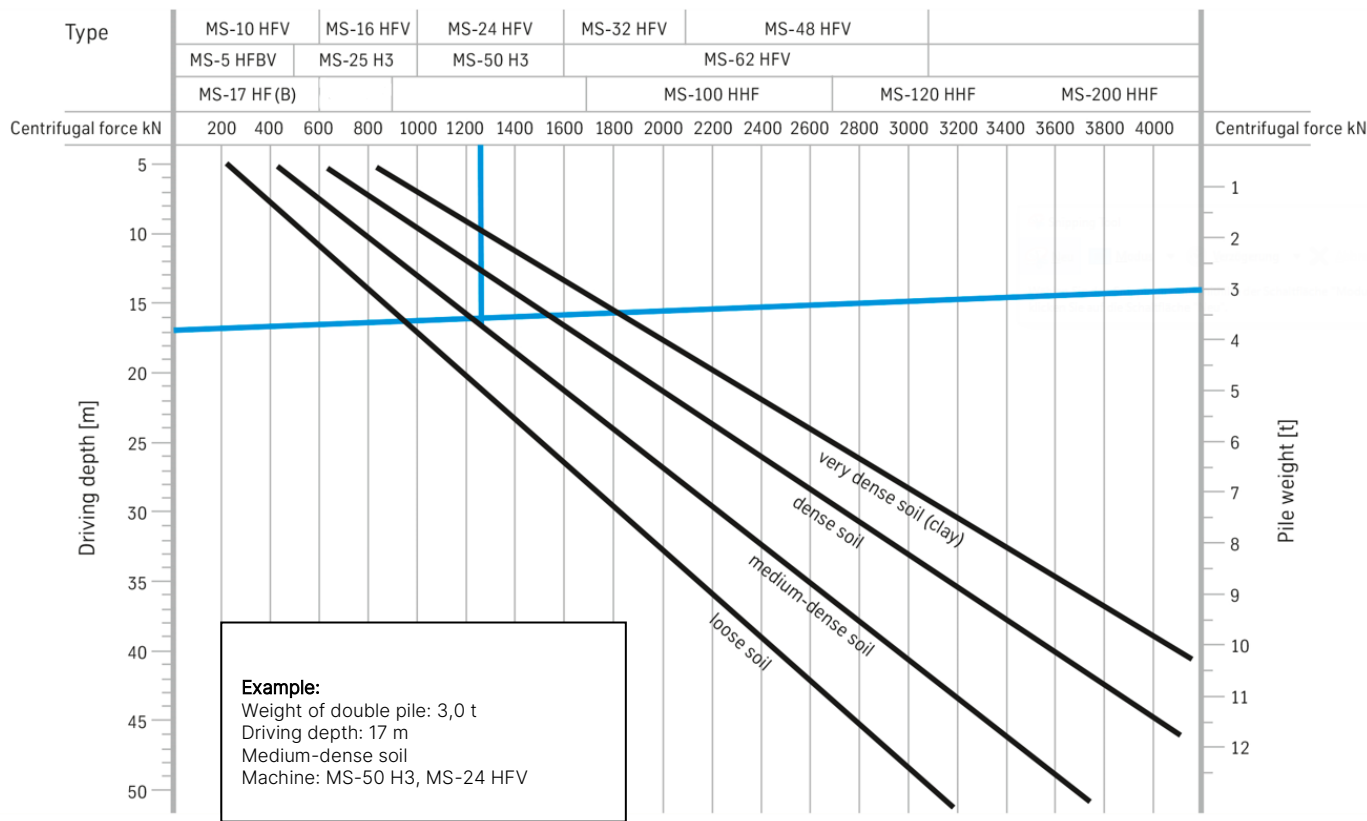
The selection guide below helps to choose the right vibratory hammer or determine the centrifugal force required depending on soil conditions, pile weight, and driving depth.

The use of additional equipment, e.g., flushing lances or pre-drilling units, can help to achieve much better driving performance with the same size or centrifugal force of the vibratory hammer.

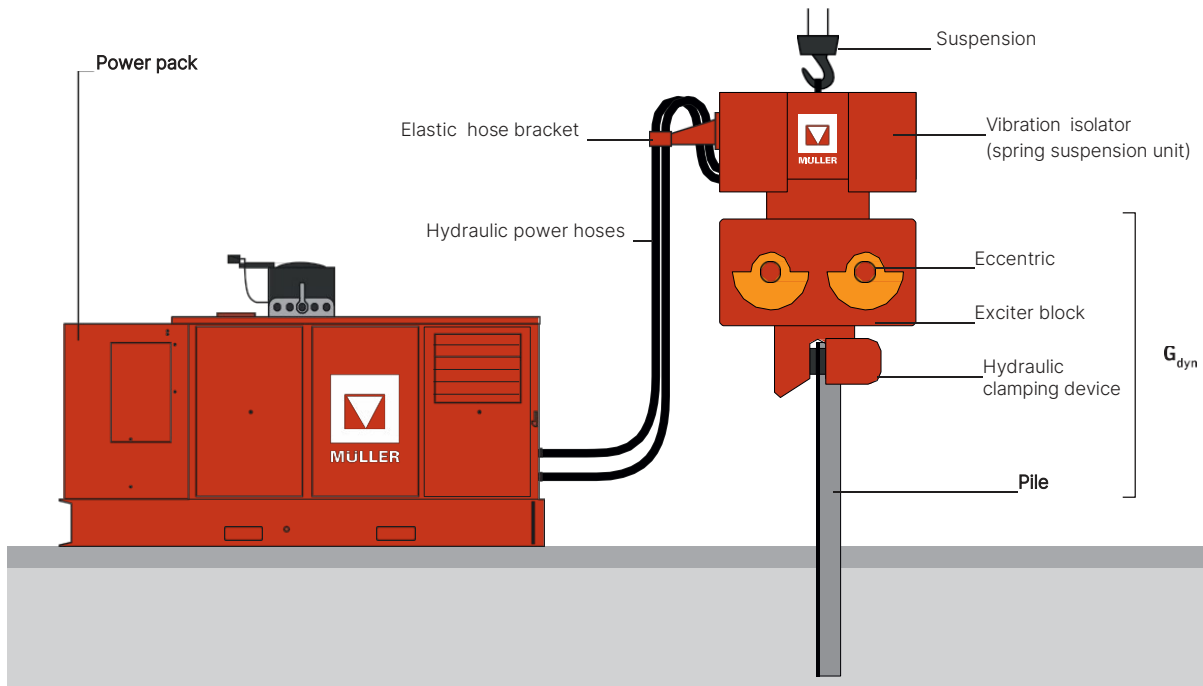
The power pack must be powerful enough to provide the necessary working torque to ensure the centrifugal force of the vibratory hammer, even in difficult soils. The drive output should be 2-3 kW per 10 kN centrifugal force.

For an exact equipment selection, depending on soil parameters and pile section data, please contact our technical consultants. They will use numerical simulation software to calculate the optimum machine for your application.

Equipment selection guide



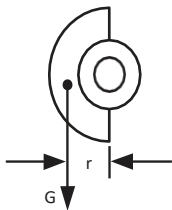
Operating principle of MÜLLER free-hanging vibratory hammers



Key formulas for vibration technology

Eccentric moment M [kgm]

$$M = G \cdot r$$



The eccentric moment is the measure of unbalance. As a determining factor for amplitude it is a key parameter for driving operations.

Speed (frequency) n [rpm]

The speed dictates the vibration frequency of the system. The vibrations are transferred via the pile to the surrounding soil, significantly reducing the surface friction between pile and soil. High frequencies counter the unwanted spread of vibrations in the soil.

Centrifugal force F [N]

$$F = M \cdot \omega^2$$

$$F = M \cdot \left(\pi \cdot \frac{n}{30} \right)^2$$

The centrifugal force must be high enough to overcome surface friction between pile and soil. Centrifugal force plays a major part in reducing surface friction and provides impact force to overcome tip resistance.

When selecting the clamping device, care must be taken to ensure that the clamping force is sufficient in relation to the vibrator's centrifugal force. The required clamping force [kN] is calculated by multiplying the centrifugal force [kN] x factor 1,2. It is also possible to reduce the centrifugal force of the vibratory hammer at a given clamping force in order to remain within the permissible parameters. Centrifugal force [kN] x 1,2 = clamping force [kN]

Amplitude S [m]

$$S = 2s = \frac{2 \cdot M_{stat} [kgm]}{G_{dyn} [kg]}$$

Together with centrifugal force, amplitude is a measure of driving performance. A large 'stroke' and high 'impact force' ensure good driving progress. When driving and extracting in cohesive soils, the elastic connection between pile and soil can only be overcome, if the amplitude is high enough.

Acceleration a [m/s²]

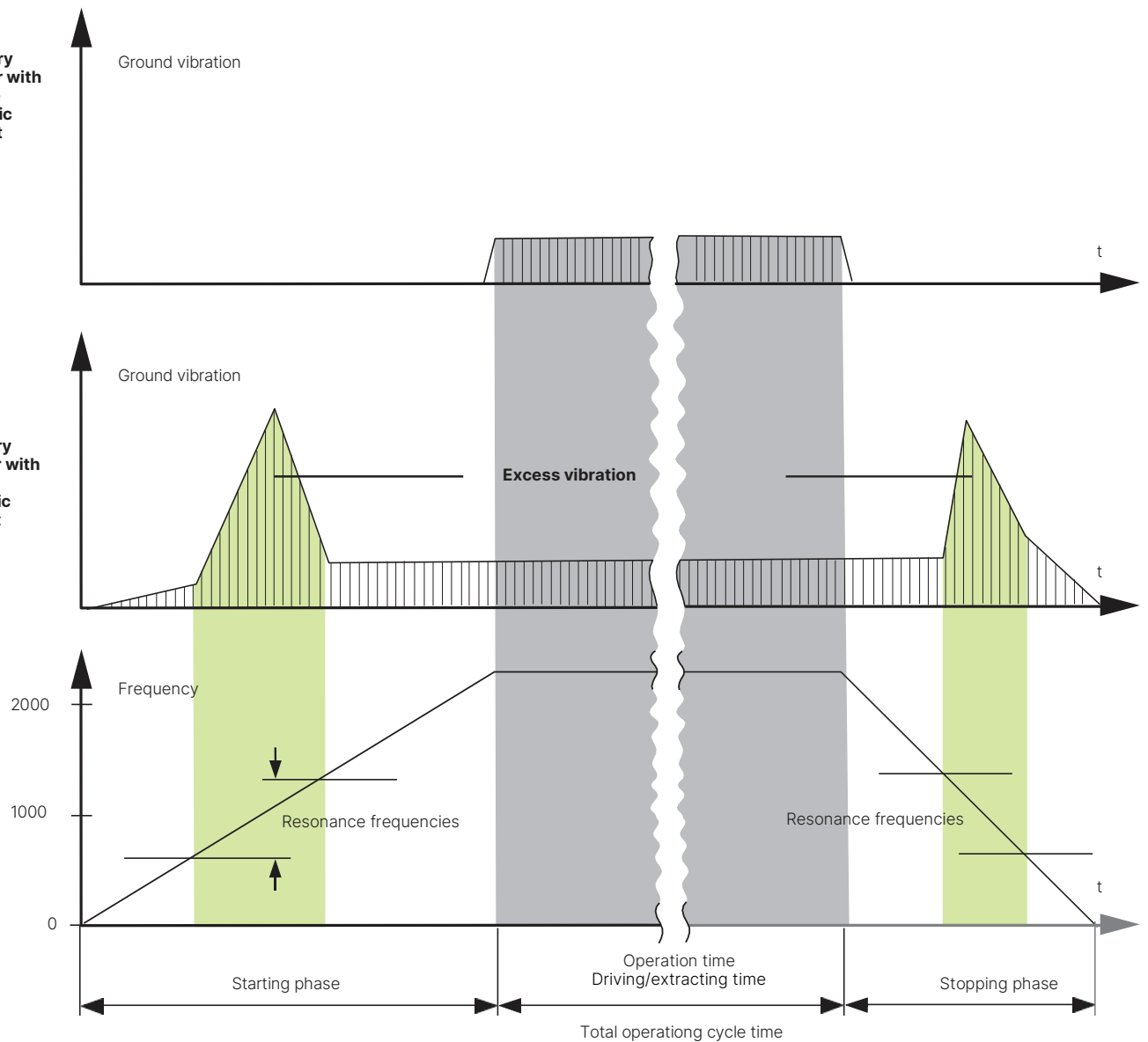
$$a = s \cdot \omega^2 \quad \text{with} \quad \omega = \pi \cdot \frac{n}{30}$$

Transmission of the pile acceleration to the surrounding soil causes the displacement of the grain structure and reduces grain friction and soil resistance. Acceleration is expressed as the ratio of acceleration of the vibrator to gravity:

$$\eta = \frac{a}{g} \quad \text{This ratio corresponds to:} \quad \eta = \frac{F \cdot 10^{-1}}{G_{dyn}}$$

The value can lie between 10 and 30.

Principle of resonance-free starting and stopping



MÜLLER vibratory hammers H series

Type			MS-25 H3	MS-35 H3	MS-50 H3	MS-65 H3
Centrifugal force	F (max.)	kN	774	834	1.430	1.670
Eccentric moment	M stat	kgm	25	32,5	50	65
Frequency	f (max.)	min ⁻¹	28,0	25,5	26,9	25,5
Speed	n (max.)	Hz	1.680	1.530	1.615	1.530
Pulling force	F pull (max.)	kN	400	400	500	500
Weight total	without clamping device	kg	3.600	3.600	7.905	8.200
Weight dynamic	without clamping device	kg	2.550	2.660	3.820	4.200
Amplitude	without clamping device/pile	mm	19,6	24,4	26,2	31,0
Power consumption	P (max.)	kW	248	270	419	450 / 397
Required oil flow	Q motor (max.)	l/min	425	463	719	773 / 680
Operating pressure	p (max.)	bar	350	350	350	350
Dimensions	Length L	mm	2.250	2.250	2.800	2.800
	Width B	mm	761	761	722	737
	Height H	mm	1.760	1.760	2.140	2.140
	Throat T	mm	402	402	402	402
Single clamping device	Type	MS-U	80/100	80/100	180	200
	alternative	MS-U	150	150	–	250
Double clamping device	Type	MS-U	2 x 54	2 x 54	2 x 80/100	2 x 80/100
	alternative	MS-U	2 x 80/100	2 x 80/100	2 x 90	–
Recommended power pack	Type	MS-A	340 o. 280	340 o. 280	420	570 o. 420

Fixed eccentric moment

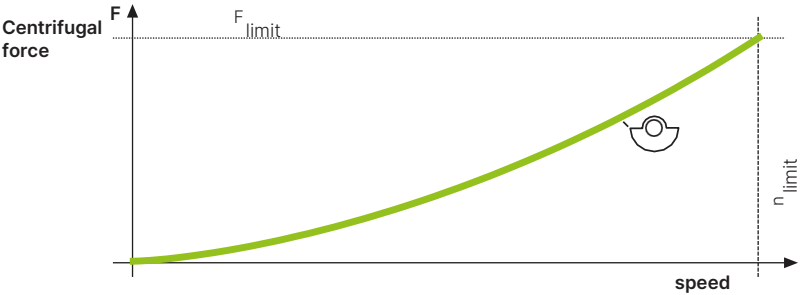
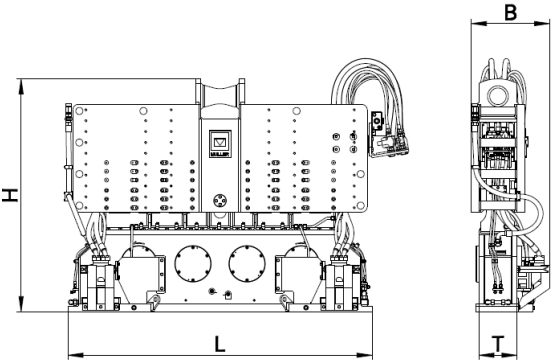
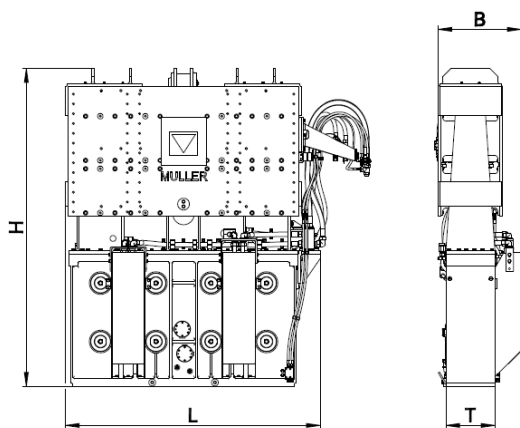


Image shows MS 50 H3

MÜLLER vibratory hammers HHF series

Type			MS-100 HHF	MS-120 HHF	MS-220 HHF	MS-240 HHF
Centrifugal force	F (max.)	kN	2.500	3.003	4.686	5.160
Eccentric moment	M stat (max.)	kgm	100	116	218	240
	Steps (see illustration)	kgm	48 / 60 / 80 / 100	80 / 94 / 110 / 116	151 / 175 / 193 / 218	151 / 193 / 218 / 240
Frequency steps	f (max.)	Hz	36 / 32 / 27,8 / 25	30,9 / 28,3 / 26,2 / 25,6	27,5 / 26 / 24,5 / 23,3	29,5 / 26 / 24,5 / 23,3
Speed steps	n (max.)	min ⁻¹	2.160 / 1.920 / 1.670 / 1.500	1.850 / 1.700 / 1.570 / 1.536	1.650 / 1.560 / 1.470 / 1.400	1.770 / 1.560 / 1.470 / 1.400
Pulling force	F pull (max.)	kN	600	1.200	1.200	1.200
Weight total	without clamping device	kg	10.900	15.500	20.100	20.100
Weight dynamic	without clamping device	kg	7.700	8.900	11.980	12.010
Amplitude	without clamping device / pile	mm	12,5 / 15,6 / 20,8 / 26,0	18,0 / 21,1 / 24,7 / 26,1	25,2 / 29,2 / 32,2 / 36,4	25,1 / 32,1 / 36,3 / 40,0
Power consumption	P (max.)	kW	750 / 610	895 / 671	1.015	1.032
Required oil flow	Q Motor (max.)	l/min	1.286 / 1.045	1.534 / 1.150	1.740	1.770
Operation pressure	p (max.)	bar	350	350	350	350
Dimensions	Length L	mm	2.410	2.310	2.300	2.300
	Width B	mm	846	1.200	1.513	1.513
	Height H	mm	3.235	4.135	4.190	4.190
	Throat T	mm	500	832	832	832
Single clamping device	Type	MS-U	360	360	360*	360*
	Alternative	MS-U	–	–	–	–
Double/quadruple	Type	MS-U	2 x 150	2 x 180	4 x 180	4 x 180
clamping device	Alternative	MS-U	2 x 180	–	2 x 250*	2 x 250*
Recommended power pack	Type	MS-A	840 / 690 o. 700	1200 o. 1150 / 840	1200 o. 1150	1200 o. 1150

* Only permitted with reduced centrifugal force



Stepwise adjustable eccentric moment

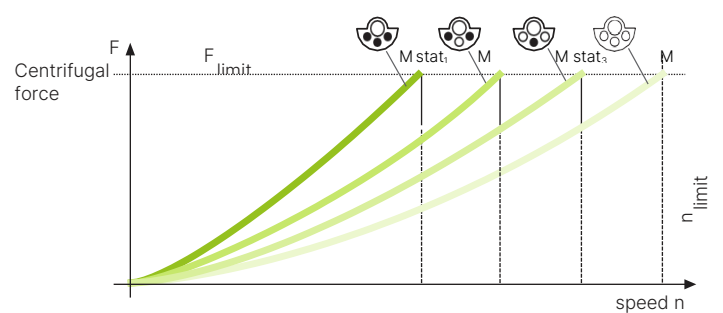
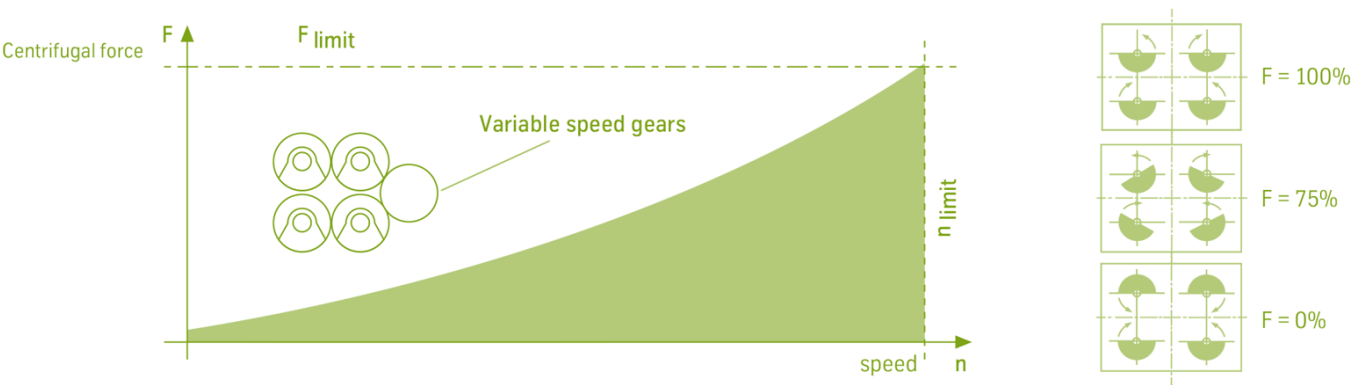


Image shows MS 100 HHF

MÜLLER vibratory hammers HFV series

Type			MS-10 HFV	MS-12 HFV	MS-16 HFV	MS-20 HFV	MS-24 HFV
Centrifugal force	F (max.)	kN	610	740	985	1.200	1.405
Eccentric moment	M stat (variable)	kgm	0-10	0-12,3	0-16	0-19,5	0-24
Frequency	f (max.)	Hz	39,3	39,0	39,5	39,5	38,5
Speed	n (max.)	min ⁻¹	2.358	2.340	2.370	2.370	2.310
Pulling force	F pull (max.)	kN	180	210	300	300	400
Weight total	without clamping device	kg	2.350	2.350	3.530	3.600	5.150
Weight dynamic	without clamping device	kg	1.750	1.750	2.565	2.530	2.900
Amplitude	without clamping device/pile	mm	11,8	14,1	12,5	15,4	16,5
Power consumption	P (max.)	kW	148 / 203	165 / 229	222 / 298	298 / 408	290 / 398
Required oil flow	Q Motor (max.)	l/min	254 / 348	283 / 393	380 / 511	511 / 700	498 / 682
Operating Pressure	p (max.)	bar	350	350	350	350	350
Dimensions	Length L	mm	1.797	1.797	2.080	2.080	2.110
	Width B	mm	732	789 / 839	782	782	866 / 956
	Height H	mm	1.560	1.560	2.060	2.060	2.210
	Throat T	mm	330	330	350	350	451
Single clamping device	Type	MS-U	80/100	80/100	150	150	180
Double clamping device	Type	MS-U	2 x 54	2 x 54	2 x 80/100	2 x 80/100	2 x 80/100
Recommended power pack	Type	MS-A	190	190	280	340	340
	Type	MS-A	280	280	340	420	420

Variable eccentric moment



MÜLLER vibratory hammers HFV-Series

Typ			MS-28 HFV	MS-32 HFV	MS-40 HFV	MS-48 HFV	MS-62 HFV
Centrifugal force	F (max.)	kN	1.500	1.980	2.005	2.905	3.000
Eccentric moment	M stat (variable)	kgm	0-28	0-32	0-39,2	0-48	0-62
Frequency	f (max.)	Hz	36,8	39,6	36,0	39,2	35,0
Speed	n (max.)	min ⁻¹	2.210	2.375	2.160	2.350	2.100
Pulling force	F pull (max.)	kN	500	600	600	600	800
Weight total	without clamping device	kg	5.200	7.250	7.430	9.700	11.165
Weight dynamic	without clamping device	kg	2.950	4.850	5.020	6.520	6.805
Amplitude	without clamping device/pile	mm	18,0	13,2	15,6	14,7	18,2
Power consumption	P (max.)	kW	380 / 518	499 / 610	500 / 630	645 / 821	734 / 960
Required oil flow	Q Motor (max.)	l/min	652 / 888	855 / 1.046	857 / 1.080	1.105 / 1.408	1.258 / 1.646
Operating Pressure	p (max.)	bar	350	350	350	350	350
Dimensions	Length L	mm	2.110	2.465	2.465	2.465	2.465
	Width B	mm	866 / 956	800	826	1.123	1.180
	Height H	mm	2.240	2.455	2.460	2.525	2.525
	Waist T	mm	451	345	437	860	860
Single clamping device	Type	MS-U	180	250	250	360	360
Double clamping device	Type	MS-U	2 x 80/100	2 x 150	2 x 150	2 x 180	2 x 180
Recommended power pack	Type	MS-A	420	570	570	690 o. 700	840
	Type	MS-A	570	690 o. 700	690 o. 700	840	1150 o. 1200

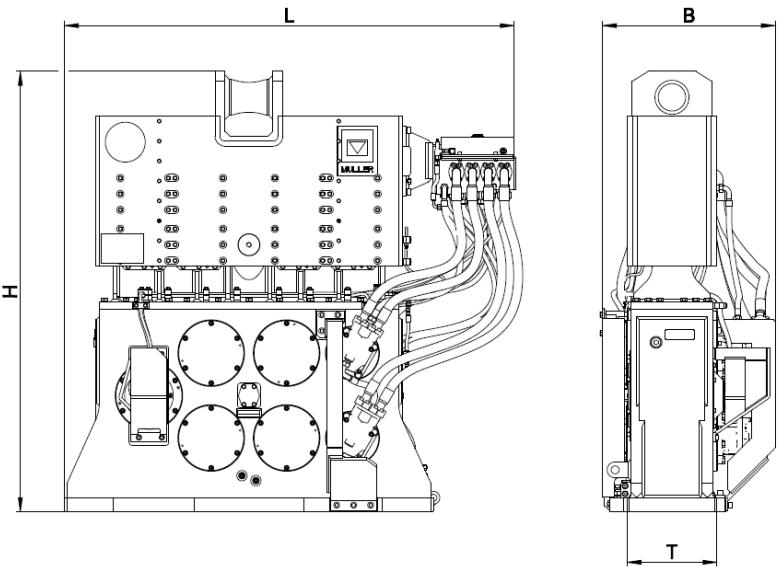


Image shows MS-24 HFV

MÜLLER power packs

EU Stage V / EPA Tier 4 final exhaust certifications

Type			MS-A 190 V	MS-A 340 V	MS-A 420 V	MS-A 690 V	MS-A 840 V	MS-A 1200 V
Diesel engine			CAT	CAT	CAT	CAT	CAT	Volvo Penta
Type			C 7.1	C 9.3B	C 15	2x C 9.3B	2x C 15	2x TWD 1683 VE
Exhaust certification		EU / EPA	V / Tier 4f	V / Tier 4f	V / Tier 4f	V / Tier 4f	V / Tier 4f	V / Tier 4f
Power	P (max.)	kW	186	340	433	680	866	1.170
Speed	n (max.)	min ⁻¹	2.000	2.000	2.000	2.100	2.000	1.800
Hydraulics								
Oil flow rate	Q (max.)	l/min	290	530	740	1.130	1.480	1.980
Operating pressure	p (max.)	bar	380	380	380	380	380	380
Fuel tank capacity		l	400	800	900	1.400	2.200	2.200
Hydraulic tank capacity		l	500	220	280	500	600	600
Weight without fuel		kg	4.700	5.600	6.800	10.600	14.000	15.500
Dimensions	Length L	mm	3.000	3.950	4.250	4.800	5.300	6.300
	Width B	mm	1.500	1.550	1.700	2.200	2.400	2.400
	Height H	mm	2.220	2.200	2.450	2.365	2.600	2.595

Other exhaust certifications

Type			MS-A 280 V	MS-A 420 V	MS-A 570 V	MS-A 700 V	MS-A 840 V	MS-A 1150 V
Diesel engine			CAT	CAT	Volvo Penta	CAT	CAT	Volvo Penta
Type			C 9.3B LRC	C 15	TAD 1643 VE	2x C 13	2x C 15	2x TAD1643VE
Exhaust certification		EU / EPA	IIIA / Tier 3	IIIA / Tier 3	II / Tier 2	IIIA / Tier 3	IIIA / Tier 3	II / Tier 2
Power	P (max.)	kW	280	433	565	708	866	1.130
Speed	n (max.)	min ⁻¹	2.200	2.000	1.850	2.100	2.000	1.850
Hydraulics								
Oil flow rate	Q (max.)	l/min	525	740	1.050	1.180	1.480	2.100
Operating pressure	p (max.)	bar	380	380	380	380	380	380
Fuel tank capacity		l	750	900	1.050	1.400	2.200	2.200
Hydraulic tank capacity		l	230	280	440	500	600	600
Weight without fuel		kg	5.300	6.200	8.500	10.300	12.500	13.800
Dimensions	Length L	mm	3.950	4.250	4.750	4.800	5.300	5.300
	Width B	mm	1.480	1.700	2.000	2.200	2.400	2.400
	Height H	mm	2.400	2.450	2.370	2.450	2.570	2.595

MÜLLER excavator-mounted vibratory hammers

HFB series with fixed eccentric moment

Type			MS-1 HFB	MS-2 HFB	MS-3 HFB	MS-4 HFB	MS-6 HFB	MS-7 HFB	MS-9 HFB	MS-17 HFB
Centrifugal force	F (max.)	kN	90	245	296	374	464	604	606	604
Eccentric moment	M stat (max.)	kgm	0,7	2,2	3,0	4,2	6,5	7,0	8,5	17,0
Frequency	f (max.)	Hz	56,0	53,1	50,0	47,5	42,5	46,7	42,5	30,0
Speed	n (max.)	min ⁻¹	3.360	3.185	3.000	2.850	2.550	2.800	2.550	1.800
Pulling force	F pull (max.)	kN	34	60	60	120	120	150	150	140
Pushing force	F push (max.)	kN	34	40	40	80	80	80	80	170
Weight total	incl. clamping device ¹	kg	350	815	830	1.230	1.240	1.300	1.380	2.445
Weight dynamic	incl. clamping device ¹	kg	230	570	585	940	950	950	990	1.690
Amplitude	incl. clamping device ¹	mm	6,1	7,7	10,3	8,9	13,7	14,7	17,2	20,1
Power consumption	P (max.)	kW	60 / 38	61	70	105	119	130	133	158
Required oil flow	Q Motor (max.)	l/min	102 / 64	105	120	180	204	224	229	270
Operation pressure	p (max.)	bar	350	350	350	350	350	350	350	350
Dimensions	Length L	mm	mm	835	1.153	1.153	1.348	1.348	1.348	1.348
	Width B	mm	mm	472	626	626	745	745	745	745
	Height H	mm	825	mm	825	1.129	1.129	1.344	1.344	1.344
	Throat T	mm	mm	230	260	260	340	340	340	340
Clamping device	Type	MS-U ¹	12	40	40	60/72	60/72	60/72	60/72	80/100
Recommended excavator	Weight	t	10 / 8	10	12	18	25	30	30	32
Recommended excavator	P	kW	75 / 50	80	90	130	150	160	170	200
Recommended power pack for free-hanging operation	Type	MS-A	–	–	–	190	190	190	190	190

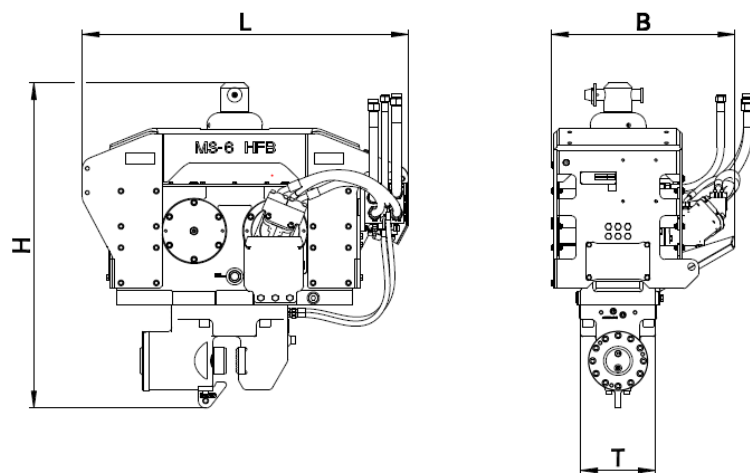
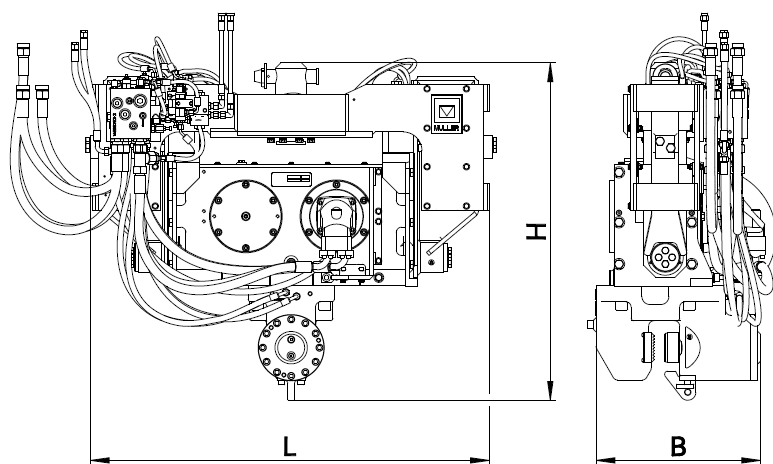


Image shows MS-6 HFB with MS-U 60/72

MÜLLER excavator-mounted vibratory hammers

HFB S series with fixed eccentric moment

Type			MS-4 HFB S	MS-6 HFB S	MS-7 HFB S
Centrifugal force	F (max.)	kN	378	464	604
Eccentric moment	M stat (max.)	kgm	4,2	6,5	7,0
Frequency	f (max.)	Hz	47,5	42,5	46,7
Speed	n (max.)	min ⁻¹	2.850	2.550	2.800
Pulling force	F pull (max.)	kN	120	120	150
Pushing force	F push (max.)	kN	80	80	80
Weight total	incl. clamping device ¹	kg	1.360	1.370	1.380
Weight dynamic	incl. clamping device ¹	kg	1.110	1.120	1.130
Amplitude	incl. clamping device ¹	mm	7,7	11,6	12,4
Power consumption	P (max.)	kW	100	119	130
Required oil flow	Q Motor (max.)	l/min	171	204	224
Operating pressure	p (max.)	bar	350	350	350
Dimensions	Length L	mm	1.520	1.520	1.520
	Width B	mm	697	697	697
	Height H	mm	1.250	1.250	1.250
	Throat T	mm	–	–	–
Clamping device	Type	MS-U ¹	60/72	60/72	60/72
Recommended excavator	Weight	t	18	23	27
Recommended excavator	P	kW	125	150	160
Recommended power pack for free-hanging operation	Type	MS-A	190	190	190



Picture shows MS-4 HFB S with MS-U 60/72

MÜLLER excavator-mounted vibratory hammers

HFBV series with variable eccentric moment

Type			MS-5 HFBV*	MS-7 HFBV*	MS-8 HFBV	MS-10 HFBV
Centrifugal force	F (max.)	kN	400	478	585	588
Eccentric moment	M stat (max.)	kgm	0–5	0–6,7	0–8	0–9,8
Frequency	f (max.)	Hz	45,0	42,5	43,0	39,0
Speed	n (max.)	min ⁻¹	2.700	2.550	2.580	2.340
Pulling force	F pull (max.)	kN	120	120	150	150
Pushing force	F Push (max.)	kN	80	80	150	150
Weight total	incl. clamping device ¹	kg	1.660	1.680	2.180	2.230
Weight dynamic	incl. clamping device ¹	kg	1.170	1.190	1.340	1.380
Amplitude	incl. clamping device ¹	mm	8,5	11,3	12,0	14,2
Power consumption	P (max.)	kW	95 / 126	112 / 126	165 / 120	167 / 148
Required oil flow 5-hose connection	Q Motor (max.)	l/min	162 / 216	204 / 230	283 / 206	293 / 257
Required oil flow 3-hose connection	Q Motor (max.)	l/min	180 / 240	220 / 250	–	–
Operating pressure	p (max.)	bar	350	350	350	350
Dimensions	Length L	mm	1.395	1.395	1.554	1.554
	Width B	mm	707	707	761	761
	Height H	mm	1.544	1.544	1.582	1.582
	Throat T	mm	390	390	415	415
Clamping device	Type	MS-U ¹	60/72	60/72	60/72	60/72
Recommended excavator	Weight	t	18	23	30	35
Recommended excavator	P	kW	120 / 155	150 / 170	150 / 205	175 / 185
Recommended power pack for free-hanging operation	Type	MS-A	190	190	190	190

*Option: with three or five connecting hoses

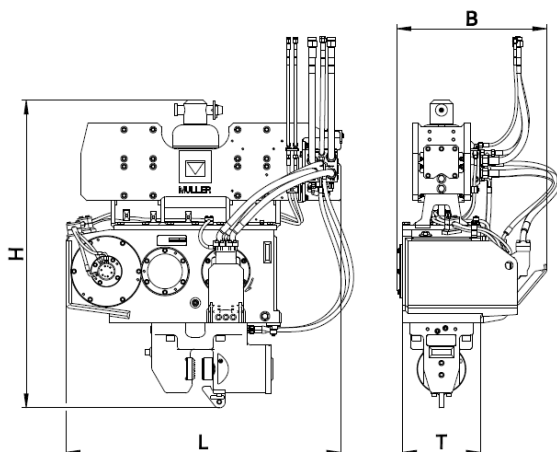


Image shows MS-5 HFBV with MS-U 60/72

MÜLLER side-grip excavator-mounted vibratory hammers

HFB SG series with fixed eccentric moment

Type			MS-4 HFB SGL	MS-4 HFB SG	MS-6 HFB SG	MS-7 HFB SG
Centrifugal force	F (max.)	kN	305	374	464	500
Eccentric moment	M stat (max.)	kgm	3,8	4,2	6,6	7,0
Frequency	f (max.)	Hz	45,0	47,5	42,5	42,5
Speed	n (max.)	min-1	2.700	2.850	2.550	2.550
Pulling force	F pull (max.)	kN	120	120	120	120
Pushing force	F Push (max.)	kN	120	120	120	120
Weight total	incl. clamping device ²	kg	1.840	2.245	2.255	2.260
Weight dynamic	incl. clamping device ²	kg	995	1.235	1.245	1.250
Amplitude	incl. clamping device ²	mm	7,6	6,7	10,5	11,2
Power consumption	P (max.)	kW	95 / 79	100	119	119
Required oil flow	Q motor (max.)	l/min	162 / 135	171	204	204
Operating pressure	p (max.)	bar	350	350	350	350
Dimensions	Length L	mm	1.443	1.455	1.455	1.455
	Width B	mm	1.031	1.057	1.057	1.057
	Height H	mm	1.533	1.533	1.526	1.526
Clamping device	MS-U ²		40	60/72	60/72	60/72
Alternative clamping device	MS-U		60/72 K	60/72 K	60/72 K	60/72 K
Side clamping device for beams and piles	MS-U ²		43 SG	43 SG	43 SG	43 SG
Side clamping device for pipes	MS-U		55 SGR	55 SGR	55 SGR	55 SGR
Recommended excavator	Weight	t	15	20	25	25
Recommended excavator	P	kW	120 / 100	125	150	150

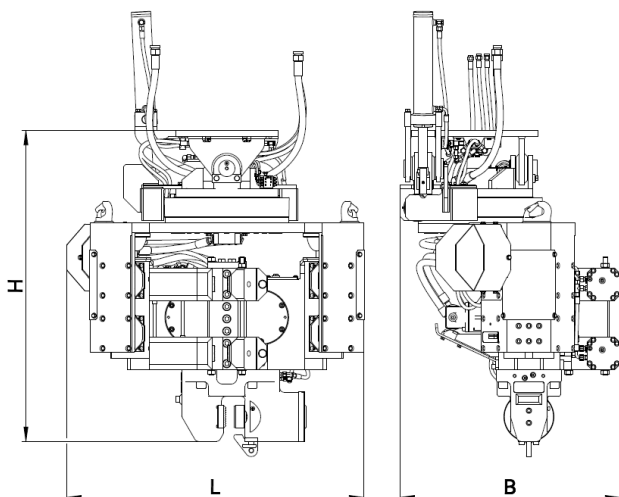


Image shows MS-4 HFB SG with MS-U 43 SG and MS-U 60/7

HFBV SGX-Series with fixed static moment

Typ			MS-6 HFBV SGX	MS-8 HFBV SGX	MS-10 HFBV SGX
Centrifugal force	F (max.)	kN	480	663	685
Eccentric moment	M stat (max.)	kgm	0-6	0-8	0-9,8
Frequency	f (max.)	Hz	45	46	42
Speed	n (max.)	min ⁻¹	2.700	2.750	2.525
Pulling force	F pull (max.)	kN	150	150	150
Pushing force	F Push (max.)	kN	150	150	150
Weight total	incl. clamping device ²	kg	3.592	4.027	4.041
Weight dynamic	incl. clamping device ²	kg	2.220	2.655	2.669
Amplitude	incl. clamping device ²	mm	6,1	8,1	9,8
Power consumption	P (max.)	kW	126	173	184
Required oil flow	Q motor (max.)	l/min	216	297	316
Operating pressure	p (max.)	bar	350	350	350
Dimensions	Length L	mm	1.630	1.630	1.630
	Width B	mm	1.391	1.391	1.389
	Height H	mm	1.984	1.986	1.984
Clamping device	MS-U ²		60/72	80/100	80/100
Alternative clamping device	MS-U		60/72 K	-	-
Side clamping device for beams and piles	MS-U ²		43 SG	43 SG	43 SG
Recommended excavator	Weight	t	28	30	30
Recommended excavator	P	kW	160	220	230

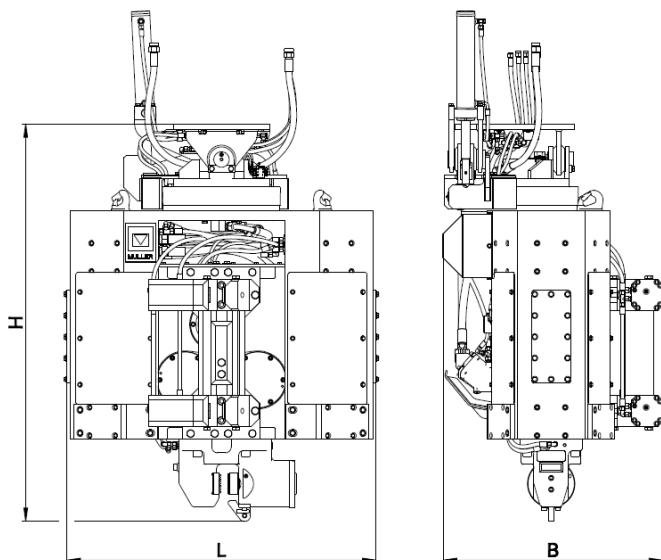
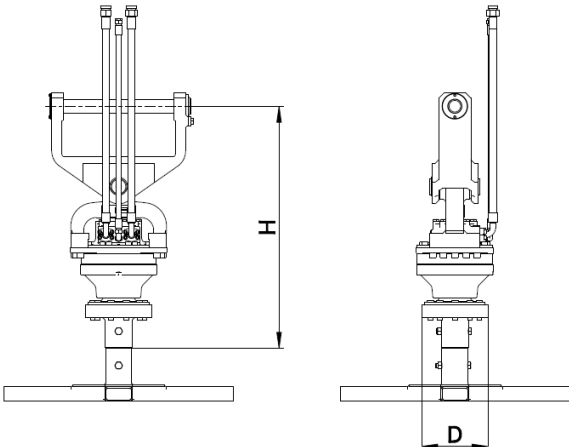


Image shows MS-6 HFBV SGX with MS-U 43 SG and MS-U 60/70

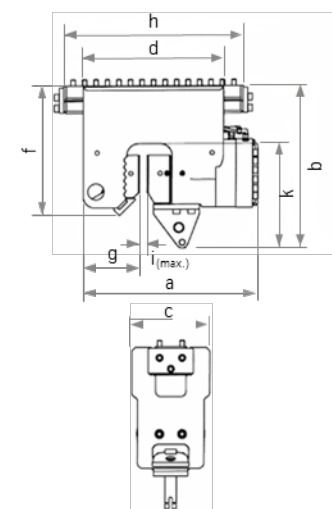
MÜLLER excavator-mounted drill drives RHA series

Type			MS-RHA 12 3*	MS-RHA 16 3*	MS-RHA 24 3*	MS-RHA 34 3*	MS-RHA 46 3*
Torque	M (max.)	Nm	12.000	16.000	24.000	34.000	46.000
Speed	n (max.)	min ⁻¹	30-125	30-115	30-110	30-100	30-70
Operating pressure	p (max.)	bar	80-350	80-350	80-350	80-350	80-350
Power consumption	P	kW	10-152	15-204	17-268	24-350	35-350
Required oil flow	Q motor (max.)	l/min	65-260	95-350	130-460	180-600	260-600
Diameter	Smallest drilling diameter	mm	200	200	400	400	400
Diameter	Largest drilling diameter	mm	700	900	1.200	1.400	1.600
Drill depth	With smallest drilling diameter (max.)	m	20	25	14	16	20
Drill depth	With largest drilling diameter (max.)	m	4	4	2	2	2
Weight	without auger/without stand	kg	300	360	440	600	760
Dimensions	Height H	mm	983	1.149	1.148	1.234	1.240
	Diameter D	mm	425	400	390	485	555
Hexagon connection		mm	70 / 70	70 / 80	80 / 80	100 / 100	120 / 120
Recommended excavator	Weight	t	10-20	15-25	20-30	28-40	35-50
Recommended excavator	P	kW	80-125	120-150	125-220	160-438	144-438

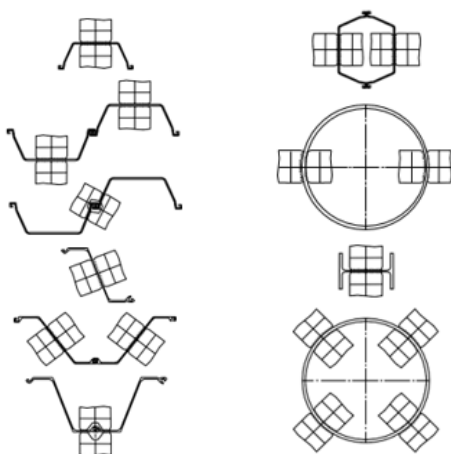
*Connection to excavator stick
Options available upon request: mounted on leader, clamped into vibratory hammer clamping device



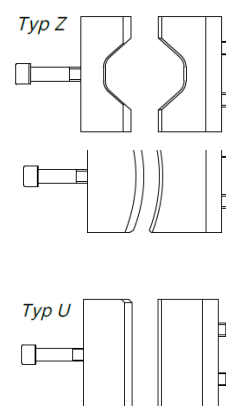
MÜLLER clamping devices



Dimensions of clamping device



Arrangement of clamps



Jaw pad types

Clamping devices for bolted mounting:

Type	Clamping force kN	Clamping pressure bar	Dimensions in mm							i.	IPB	Weight
			a	c	d	f	g	h	max.	min	kg	
MS-U 12	122	260	229	195	195	223	95	–	15	120	50	
MS-U 40	370	300	548	260	400	285	175	–	40	120	145	
MS-U 60/72	600 / 720	300 / 358	640	320	480	350	220	–	40	140	260	
MS-U 80/100 A	800 / 1.000	280 / 350	798,5	330	519	410	216,5	–	48	280	400	
MS-U 150 AP	1.500	350	902	360	660	580	319	–	40	320	940	
MS-U 180 AP	1.800	350	893	390	740	645	314	–	80	320	1.130	
MS-U 200 A	2.000	350	1.011	380	880	800	440	–	36/48	450	1.600	
MS-U 250 A	2.500	350	1.173	395	860	840	380	–	63	450	1.950	
MS-U 360 A	3.600	350	1.255	460	1.180	950	520	–	80	400	3.130	

Clamping devices to be moved on a clamping bar:

Type	Clamping force kN	Clamping pressure bar	Dimensions in mm							i.	IPB	Weight
			a	c	d	f	g	h	max.	min	kg	
MS-U 54	540	350	648	270	515	694	190	730	22	180	440	
MS-U 80/100 G	800 / 1.000	280 / 350	760	340	580	509	206,5	–	48	–	670	
MS-U 90	900	350	770	340	580	529	290	820	28	180	515	
MS-U 100 GP	1.000	350	761	345	610	534	245 / 250	780	33 / 50	280	750	
MS-U 150 GP	1.500	350	892	340	640	554	309	780	45	320	920	
MS-U 180 GP	1.800	350	903	390	745	645	325	880	80	320	1.250	
MS-U 250 G	2.500	350	1.173	398	860	840	364	1.150	63	450	2.450	

MÜLLER accessories

Intermediate plates and brackets for free hanging vibratory hammers

Intermediate plate / bracket	Compatible with (vibratory hammer)	Compatible with (pile-driving material)
Intermediate plate, standard	MS-24 up to MS-32 HFV and MS-100 HHF	Standard version for double piles (U-profile)
Intermediate plate, narrow	MS-24 up to MS-32 HFV and MS-100 HHF	Narrow version for double piles (U-profile)
Pipe bracket MS-KRH 1800	MS-16 up to MS-40 HFV	Adaptation up to max. 1.800 mm pipe diameter*
Pipe bracket MS-KR 2800	MS-24 up to MS-62 HFV / MS-100 and MS-120 HHF	Adaptation up to max. 2.800 mm pipe diameter*
X-Bracket MS-KX 2800	MS-220 and MS-240 HHF	Adaptation up to max. 2.800 mm pipe diameter
X-Bracket MS-KX 4500	MS-220 and MS-240 HHF	Adaptation up to max. 4.500 mm pipe diameter

*Other diameters available upon request.

*Depending on the clamping device-configuration.

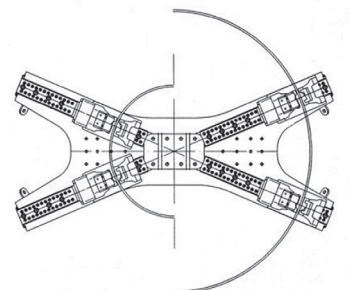


Image shows X-Bracket

Brackets for Excavator mounted vibratory hammers

Pipe bracket	Compatible with (vibratory hammer)	Compatible with (pipes)
Pipe bracket DA 1160	MS-4 up to MS-17 HFB, for MS-5 up to MS-10 HFBV	d min = ca. 400 up to d max. = ca. 850 mm

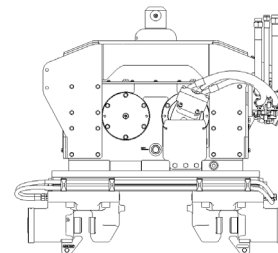


Image shows MS-9 HFB with pipe bracket DA 1160

MÜLLER ground release shackle

Type	Pulling force kN	Suitable for perforations up to mm	Weight kg
MS-SSZ-3 B	30	177	15
MS-SSZ-3 BL	30	250	19
MS-SSZ-4 B	40	306	24
MS-SSZ-5 B	50	212	26



Image shows MS-SSZ 3B

MÜLLER universal connecting fork for excavator-mounted equipment

Connecting fork	up to excavator stick width mm	Incl. pins Ø mm	Compatible with
Universal	484	60 70 80	all MÜLLER excavator-mounted vibratory hammers MS-RHA 12 3, 16 3 & 24 3

*Other connecting forks upon request

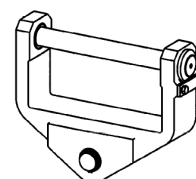


Image shows universal connecting fork

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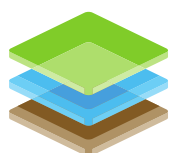
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